





## **Cobot S**

## Integrated Mobile Collaborative Robot



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## Integrated Mobile Collaborative Robot

AgileX Cobot S is a comprehensive mobile collaborative robot solution that integrates highperformance industrial computers, LiDAR, IMU, multi-DOF robotic arm, and visual perception. It can perform tasks such as autonomous navigation, motion control, visual recognition, and robotic arm grasping. It aims to address the technical complexity and high integration challenges that customers face when dealing with mobile robots in complex application scenarios. Cobot S can play a powerful role in various fields, including smart manufacturing, education and training, and scientific research.

Highlights			
Obstacle Avoidance	Motion Control		360°Visual Grasping
$\sim \rightarrow$			360
Pan-and-Tilthead	Visual Mapping		Mobile Grasping
Specifications			
Dimensions 500 x 754 x 1504mm	Weight 100kg	Ground clearance 56.5mm	Positioning Accuracy <b>±5cm</b>
Battery	Maximum Speed	Gripper Load	Navigation Method
24V60A	1.6m/s	5kg	SLAM navigation
	<ul> <li>RM75–B Robotic Arm</li> </ul>	<ul> <li>Robotic Gripper</li> </ul>	<ul> <li>Touch Screen</li> </ul>
	Work Status Indicators	<ul><li>LiDAR</li></ul>	Safety Bumper
	RGB-D Camera	Pan-and-Tilt	Router
	• X–7010 Mini Computer	• IMU	• 3D LIDAR
	Hub Motor	• Tray	<ul> <li>Turn Signa</li> </ul>
	Robotic Arm Controller	• Power Converter	Automatic Charging Pile